

An Inertial Proximal-Gradient Penalization Scheme for Constrained Convex Optimization Problems

Radu Ioan Bot¹ · Ernö Robert Csetnek¹ · Nimit Nimana²

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Abstract We propose a proximal-gradient algorithm with penalization terms and inertial and memory effects for minimizing the sum of a proper, convex, and lower semicontinuous and a convex differentiable function subject to the set of minimizers of another convex differentiable function. We show that, under suitable choices for the step sizes and the penalization parameters, the generated iterates weakly converge to an optimal solution of the addressed bilevel optimization problem, while the objective function values converge to its optimal objective value.

Keywords Proximal-gradient algorithm \cdot Inertial algorithm \cdot Penalization \cdot Fenchel conjugate

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Dedicated to Professor Michel Théra's 70th birthday.

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 Radu Ioan Boţ radu.bot@univie.ac.at
 Ernö Robert Csetnek ernoe.robert.csetnek@univie.ac.at
 Nimit Nimana nimitn@hotmail.com

- Faculty of Mathematics, University of Vienna, Oskar-Morgenstern-Platz 1, 1090 Vienna, Austria
- Department of Mathematics, Faculty of Science, Naresuan University, Phitsanulok, 65000, Thailand



1 Introduction and Preliminaries

Let \mathcal{H} be a real Hilbert space with inner product $\langle \cdot, \cdot \rangle$ and associated norm $\| \cdot \|$. Let $f: \mathcal{H} \to \overline{\mathbb{R}} = \mathbb{R} \cup \{\pm \infty\}$ be a proper, convex, and lower semicontinuous function, and $h: \mathcal{H} \to \mathbb{R}$ and $g: \mathcal{H} \to \mathbb{R}$ be convex and differentiable functions with Lipschitz continuous gradients with positive Lipschitz constants L_h and L_g , respectively. We consider the bilevel optimization problem

$$\min_{x \in \arg\min g} f(x) + h(x) \tag{1}$$

and assume that the set

$$S := \arg\min\{f(x) + h(x) : x \in \arg\min g\}$$

is nonempty. We also assume without loss of generality that min g = 0.

The work of Attouch and Czarnecki [5] has represented the starting point of a series of articles approaching the minimization of a smooth or (sometimes) a complexly structured nonsmooth objective function subject to the set of minimzers of another function, from either a discrete perspective through iterative numerical algorithms or a continuous one through dynamical systems (see [4–8, 11, 17–19, 24–27, 30, 37, 39]). The function determining the feasible set is evaluated in both settings in the spirit of penalty methods and contributes to the convergence of the generated sequences, in the discrete setting, and to the asymptotic convergence of the generated trajectories, in the continuous setting, to an optimal solution of the underlying bilevel optimization problem. We emphasize in particular the proximal-gradient algorithm with penalty term which has been introduced in [8] and for which weak ergodic convergence has been proved.

In this paper, we consider this algorithm in the context of solving problem (1) and we enhance it with inertial and memory effects. Our aim is to provide suitable choices for the step sizes and the penalization parameters, such that the generated iterates weakly converge to an optimal solution of the problem (1), while the objective function values converge to its optimal objective value. Algorithms of inertial type follow by time discretization of differential inclusions of second-order type (see [1, 3]) and have been first investigated in the context of the minimization of a differentiable function by Polyak in [40] and Bertsekas in [14]. In the last two decades, intensive research efforts dedicated to algorithms of inertial type and to their convergence behavior can be noticed (see [1–3, 10, 20–23, 28, 29, 31–36, 38]). For a variety of situations, in particular in the context of solving real-world problems, the presence of inertial terms improves the convergence behavior of the generated sequences. It is also well-known (see [9, 13]) that enhancing the proximal-gradient algorithm with inertial effects may lead to a considerable improvement of the convergence behavior of the sequence of objective function values.

The proximal-gradient algorithm with penalization terms and inertial and memory effects we propose for solving (1) is the following.

Algorithm 1 *Initialization*: Choose positive sequences $\{\lambda_n\}_{n=1}^{\infty}$, $\{\beta_n\}_{n=1}^{\infty}$, and a nonnegative constant $\alpha \in [0, 1)$. Take arbitrary $x_0, x_1 \in \mathcal{H}$.

Iterative step: For every $n \ge 1$ and given current iterates $x_{n-1}, x_n \in \mathcal{H}$ define $x_{n+1} \in \mathcal{H}$ by

$$x_{n+1} := \operatorname{prox}_{\lambda_n f} \left(x_n + \alpha (x_n - x_{n-1}) - \lambda_n \nabla h(x_n) - \lambda_n \beta_n \nabla g(x_n) \right).$$



For $x \in \mathcal{H}$ we denote by $\operatorname{prox}_{\lambda_n f}(x)$ the proximal point of the function f of parameter λ_n at x, which is the unique optimal solution of the optimization problem

$$\inf_{y \in \mathcal{H}} \left\{ f(y) + \frac{1}{2\lambda_n} \|y - x\|^2 \right\}.$$

In Algorithm 1, $\{\lambda_n\}_{n=1}^{\infty}$ denotes the sequence of step sizes, $\{\beta_n\}_{n=1}^{\infty}$ the sequence of penalization parameters, and $\alpha \in [0, 1)$ the parameter that controls the inertial terms.

The proposed numerical scheme recovers, when $\alpha = 0$, the algorithm investigated in [37] and, under the additional assumption f = 0, the gradient method of penalty type from [39]. In the case f = 0, Algorithm 1 gives rise to the gradient method of penalty type with inertial and memory effects introduced and studied in [30].

We prove weak convergence for the generated iterates to an optimal solution of (1), by making use of generalized Fejér monotonicity techniques and of the Opial lemma. The performed analysis allows us also to show the convergence of the objective function values to the optimal objective value of (1).

In the remaining of this section we recall some elements of convex analysis. For a function $f:\mathcal{H}\to\overline{\mathbb{R}}$ we denote by dom $f=\{x\in\mathcal{H}:f(x)<+\infty\}$ its effective domain and say that f is proper, if dom $f\neq\emptyset$ and $f(x)\neq-\infty$ for all $x\in\mathcal{H}$. Let $f^*:\mathcal{H}\to\overline{\mathbb{R}}$, $f^*(u)=\sup_{x\in\mathcal{H}}\{\langle u,x\rangle-f(x)\}$ for all $u\in\mathcal{H}$, be the conjugate function of f. The subdifferential of f at $x\in\mathcal{H}$, with $f(x)\in\mathbb{R}$, is the set $\partial f(x):=\{v\in\mathcal{H}:f(y)\geq f(x)+\langle v,y-x\rangle\ \forall y\in\mathcal{H}\}$. We take by convention $\partial f(x):=\emptyset$, if $f(x)\in\{\pm\infty\}$. We also denote by min $f:=\inf_{x\in\mathcal{H}}f(x)$ the optimal objective value of the function f and by arg min $f:=\{x\in\mathcal{H}:f(x)=\min f\}$ its set of global minima.

A convex and differentiable function $g:\mathcal{H}\to\mathbb{R}$ has a Lipschitz continuous gradient with Lipschitz constant $L_g>0$, if $\|\nabla g(x)-\nabla g(y)\|\leq L_g\|x-y\|$ for all $x,y\in\mathcal{H}$. It is well-known (see, for instance, [12, Theorem 18.15]) that this is equivalent to ∇g is $\frac{1}{L_g}$ -cocoercive, namely, $\langle x-y,\nabla g(x)-\nabla g(y)\rangle\geq \frac{1}{L_g}\|\nabla g(x)-\nabla g(y)\|^2$ for all $x,y\in\mathcal{H}$.

Let $M \subseteq \mathcal{H}$ be a nonempty set. The indicator function of M, $\delta_M : \mathcal{H} \to \overline{\mathbb{R}}$, is the function which takes the value 0 on M and $+\infty$ otherwise. The subdifferential of the indicator function is the normal cone of M, that is $N_M(x) = \{u \in \mathcal{H} : \langle u, y - x \rangle \leq 0 \ \forall y \in M\}$, if $x \in M$ and $N_M(x) = \emptyset$ for $x \notin M$. For $x \in M$, we have that $u \in N_M(x)$ if and only if $\sigma_M(u) = \langle u, x \rangle$, where σ_M is the support function of M, defined by $\sigma_M : \mathcal{H} \to \overline{\mathbb{R}}$, $\sigma_M(u) = \sup_{y \in M} \langle y, u \rangle$. Finally, $\operatorname{ran}(N_M)$ denotes the range of the normal cone N_M , that is, $p \in \operatorname{ran}(N_M)$ if and only if there exists $x \in M$, such that $p \in N_M(x)$.

2 Technical Lemmas

The setting in which we will carry out the convergence analysis for Algorithm 1 is settled by the following hypotheses.

Assumption 1 (I) The subdifferential sum formula $\partial(f + \delta_{\arg\min g}) = \partial f + N_{\arg\min g}$ holds;

- (II) The objective function f + h is bounded from below;
- (III) There exist positive constants η_0 , a, b, K and c > 1, such that for every $n \ge 1$:

$$0 < a \le \lambda_n \beta_n \le b < \frac{2}{L_g (1 + \eta_0)^2}, \, \frac{L_h + \beta_n L_g}{2} + \frac{\alpha - 1}{\lambda_n} \le -(1 + 2\alpha)K - c$$



and

$$\beta_{n+1} - \beta_n \le K \frac{\eta_0}{1 + \eta_0} \lambda_{n+1} \beta_{n+1};$$

(IV)
$$\{\lambda_n\}_{n=1}^{\infty} \in \ell^2 \setminus \ell^1 \text{ and } \left(\frac{1}{\lambda_{n+1}} - \frac{1}{\lambda_n}\right) \alpha \le 2 \text{ for every } n \ge 1;$$

(V)
$$\sum_{n=1}^{\infty} \lambda_n \beta_n \left[g^* \left(\frac{p}{\beta_n} \right) - \sigma_{\arg\min g} \left(\frac{p}{\beta_n} \right) \right] < +\infty \text{ for every } p \in \operatorname{ran}(N_{\arg\min g}).$$

Remark 1 For conditions which guarantee exact convex subdifferential sum formulas, we refer to [12, 15, 16, 41]. One of these conditions, which is frequently fulfilled in applications, asks for the continuity of the function f and thus does not require any knowledge of the set of minimizers of g.

The assumption in (V) originates from the work of Attouch and Czarnecki [5]; we refer to [4–8, 11, 17–19, 24–27, 30, 37, 39] for other variants, generalizations to monotone operators, and concrete examples for which this condition is satisfied (see also Remark 2).

The aim of the following three results is to derive a generalized Fejér-type inequality in the spirit of the one in the hypotheses of Lemma 4. This will be achieved in terms of the sequence $(\Gamma_n)_{n\geq 1}$, defined before Lemma 3, and which can be seen as a Lyapunov sequence equal to the sum of the objective function and a penalization of the function g both at the current iterate, and the distance of the current iterate to a fixed optimal solution.

Lemma 1 Let $u \in S$. According to the first-order optimality conditions, there exist $v \in \partial f(u)$ and $p \in N_{\arg\min g}(u)$, such that $0 = v + \nabla h(u) + p$. Set $\varphi_n := ||x_n - u||^2$ for every $n \ge 1$. Then, for every $n \ge 1$ and n > 0, it holds that

$$\begin{split} \varphi_{n+1} &- \varphi_{n} - \alpha(\varphi_{n} - \varphi_{n-1}) + \lambda_{n} \beta_{n} \left[\frac{2}{L_{g}(1+\eta)} - (1+\eta)\lambda_{n} \beta_{n} \right] \|\nabla g(x_{n})\|^{2} \\ &+ \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} g(x_{n}) \leq 2\alpha \|x_{n} - x_{n-1}\|^{2} + \|x_{n+1} - x_{n}\|^{2} \\ &+ \frac{4(1+\eta)}{\eta} \lambda_{n}^{2} \|\nabla h(u) + v\|^{2} \\ &+ \lambda_{n} \left[\frac{4(1+\eta)}{\eta} \lambda_{n} - \frac{2}{L_{h}} \right] \|\nabla h(x_{n}) - \nabla h(u)\|^{2} \\ &+ \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right) \right]. \end{split}$$
 (2)

Proof Set $y_n := x_n + \alpha(x_n - x_{n-1})$ for every $n \ge 1$. Since $y_n - x_{n+1} - \lambda_n \nabla h(x_n) - \lambda_n \beta_n \nabla g(x_n) \in \lambda_n \partial f(x_{n+1})$ and $v \in \partial f(u)$, the monotonicity of ∂f guarantees that

$$\langle y_n - x_{n+1} - \lambda_n \nabla h(x_n) - \lambda_n \beta_n \nabla g(x_n) - \lambda_n v, x_{n+1} - u \rangle \geq 0 \quad \forall n \geq 1$$

or, equivalently,

$$2\langle y_n - x_{n+1}, u - x_{n+1} \rangle \le 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + \beta_n \nabla g(x_n) + v \rangle \quad \forall n \ge 1.$$
 (3)

We notice that for every $n \ge 0$

$$2\langle x_n - x_{n+1}, u - x_{n+1} \rangle = \varphi_{n+1} - \varphi_n + ||x_{n+1} - x_n||^2$$
(4)



and so for every $n \ge 1$

$$2\alpha \langle x_{n} - x_{n-1}, u - x_{n+1} \rangle = 2\alpha \langle x_{n} - x_{n-1}, u - x_{n} \rangle + 2\alpha \langle x_{n} - x_{n-1}, x_{n} - x_{n+1} \rangle$$

$$\geq \alpha (\|x_{n-1} - u\|^{2} - \|x_{n} - u\|^{2} - \|x_{n} - x_{n-1}\|^{2})$$

$$+ \alpha (-\|x_{n} - x_{n-1}\|^{2} - \|x_{n+1} - x_{n}\|^{2})$$

$$= \alpha (\varphi_{n-1} - \varphi_{n}) - 2\alpha \|x_{n} - x_{n-1}\|^{2}$$

$$- \alpha \|x_{n+1} - x_{n}\|^{2}.$$
(5)

By employing (4) and (5) in inequality (3), we obtain for every $n \ge 1$

$$\varphi_{n+1} - \varphi_n - \alpha(\varphi_n - \varphi_{n-1}) + (1 - \alpha) \|x_{n+1} - x_n\|^2 - 2\alpha \|x_n - x_{n-1}\|^2$$

$$\leq 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + \beta_n \nabla g(x_n) + v \rangle$$

$$= 2\lambda_n \langle u - x_{n+1}, \beta_n \nabla g(x_n) \rangle + 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + v \rangle$$

$$= 2\lambda_n \langle u - x_n, \beta_n \nabla g(x_n) \rangle + 2\lambda_n \langle x_n - x_{n+1}, \beta_n \nabla g(x_n) \rangle$$

$$+ 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + v \rangle.$$
(6)

Next, we evaluate the first two terms on the right-hand side in the above statement. Since ∇g is $\frac{1}{L_g}$ -cocoercive, we have

$$\langle \nabla g(x_n) - \nabla g(u), x_n - u \rangle \ge \frac{1}{L_g} \|\nabla g(x_n) - \nabla g(u)\|^2 \quad \forall n \ge 1,$$

and from here, since $\nabla g(u) = 0$,

$$\langle \nabla g(x_n), u - x_n \rangle \le -\frac{1}{L_n} \|\nabla g(x_n)\|^2 \quad \forall n \ge 1.$$
 (7)

On the other hand, since g is convex and differentiable, we have

$$0 = g(u) > g(x_n) + \langle \nabla g(x_n), u - x_n \rangle \quad \forall n > 1$$

or, equivalently,

$$\langle \nabla g(x_n), u - x_n \rangle \le -g(x_n) \quad \forall n \ge 1.$$
 (8)

From (7) and (8) we obtain for all $n \ge 1$

$$2\lambda_n \beta_n \langle \nabla g(x_n), u - x_n \rangle \le -\frac{2}{L_g(1+\eta)} \lambda_n \beta_n \|\nabla g(x_n)\|^2 - \frac{2\eta}{1+\eta} \lambda_n \beta_n g(x_n). \tag{9}$$

For the term $2\lambda_n \beta_n \langle x_n - x_{n+1}, \nabla g(x_n) \rangle$ in (6) we have for all $n \ge 1$ the following estimate

$$2\lambda_n \beta_n \langle x_n - x_{n+1}, \nabla g(x_n) \rangle \le \frac{1}{1+n} \|x_{n+1} - x_n\|^2 + (1+\eta)\lambda_n^2 \beta_n^2 \|\nabla g(x_n)\|^2.$$
 (10)

Employing the inequalities (9) and (10) in (6), we obtain for every $n \ge 1$ that

$$\begin{aligned} \varphi_{n+1} - \varphi_n &- \alpha (\varphi_n - \varphi_{n-1}) + (1 - \alpha) \|x_{n+1} - x_n\|^2 - 2\alpha \|x_n - x_{n-1}\|^2 \\ &\leq -\frac{2}{L_g(1 + \eta)} \lambda_n \beta_n \|\nabla g(x_n)\|^2 - \frac{2\eta}{1 + \eta} \lambda_n \beta_n g(x_n) \\ &+ \frac{1}{1 + \eta} \|x_{n+1} - x_n\|^2 + (1 + \eta) \lambda_n^2 \beta_n^2 \|\nabla g(x_n)\|^2 \\ &+ 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + v \rangle, \end{aligned}$$



and further

$$\varphi_{n+1} - \varphi_n - \alpha(\varphi_n - \varphi_{n-1}) + \left[\frac{2}{L_g(1+\eta)} - (1+\eta)\lambda_n \beta_n \right] \lambda_n \beta_n \|\nabla g(x_n)\|^2
\leq 2\alpha \|x_n - x_{n-1}\|^2 - \frac{2\eta}{1+\eta} \lambda_n \beta_n g(x_n)
+ \left[\frac{1}{1+\eta} + \alpha - 1 \right] \|x_{n+1} - x_n\|^2
+ 2\lambda_n \langle u - x_{n+1}, \nabla h(x_n) + v \rangle.$$
(11)

Not least,

$$\begin{aligned} 2\lambda_{n}\langle u - x_{n+1}, \nabla h(x_{n}) + v \rangle &= 2\lambda_{n}\langle u - x_{n}, \nabla h(x_{n}) + v \rangle \\ &+ 2\lambda_{n}\langle x_{n} - x_{n+1}, \nabla h(x_{n}) + v \rangle \\ &\leq 2\lambda_{n}\langle u - x_{n}, \nabla h(x_{n}) + v \rangle \\ &+ \frac{\eta}{2(1+\eta)} \|x_{n+1} - x_{n}\|^{2} \\ &+ \frac{2(1+\eta)}{\eta} \lambda_{n}^{2} \|\nabla h(x_{n}) + v\|^{2} \\ &\leq 2\lambda_{n}\langle u - x_{n}, \nabla h(x_{n}) + v \rangle \\ &+ \frac{\eta}{2(1+\eta)} \|x_{n+1} - x_{n}\|^{2} \\ &+ \frac{4(1+\eta)}{\eta} \lambda_{n}^{2} \|\nabla h(x_{n}) - \nabla h(u)\|^{2} \\ &+ \frac{4(1+\eta)}{\eta} \lambda_{n}^{2} \|\nabla h(u) + v\|^{2} \end{aligned}$$

and by employing this estimate in (11), we deduce that for every $n \ge 1$

$$\varphi_{n+1} - \varphi_n - \alpha(\varphi_n - \varphi_{n-1}) + \lambda_n \beta_n \left[\frac{2}{L_g(1+\eta)} - (1+\eta)\lambda_n \beta_n \right] \|\nabla g(x_n)\|^2
+ \frac{\eta}{1+\eta} \lambda_n \beta_n g(x_n) \le 2\alpha \|x_n - x_{n-1}\|^2
+ \left[\frac{1}{1+\eta} + \frac{\eta}{2(1+\eta)} + \alpha - 1 \right] \|x_{n+1} - x_n\|^2
+ \frac{4(1+\eta)}{\eta} \lambda_n^2 \|\nabla h(x_n) - \nabla h(u)\|^2
+ \frac{4(1+\eta)}{\eta} \lambda_n^2 \|\nabla h(u) + v\|^2
- \frac{\eta}{1+\eta} \lambda_n \beta_n g(x_n) + 2\lambda_n \langle u - x_n, \nabla h(x_n) + v \rangle. \quad (12)$$



By using the $\frac{1}{L_h}$ -cocoercivity of ∇h we obtain for every $n \geq 1$ that

$$2\lambda_{n}\langle u - x_{n}, \nabla h(x_{n}) + v \rangle - \frac{\eta}{1+\eta}\lambda_{n}\beta_{n}g(x_{n})$$

$$= 2\lambda_{n}\langle u - x_{n}, \nabla h(x_{n}) - \nabla h(u) \rangle + 2\lambda_{n}\langle u - x_{n}, \nabla h(u) + v \rangle - \frac{\eta}{1+\eta}\lambda_{n}\beta_{n}g(x_{n})$$

$$\leq \frac{-2\lambda_{n}}{L_{h}}\|\nabla h(x_{n}) - \nabla h(u)\|^{2} + 2\lambda_{n}\langle u - x_{n}, -p \rangle - \frac{\eta}{1+\eta}\lambda_{n}\beta_{n}g(x_{n}),$$

while, since $p \in N_{\arg\min g}(u)$, it holds that

$$-2\lambda_{n}\langle u - x_{n}, p \rangle - \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} g(x_{n})$$

$$= 2\lambda_{n}\langle x_{n}, p \rangle - \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} g(x_{n}) - 2\lambda_{n}\langle u, p \rangle$$

$$= \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} \left[\left\langle x_{n}, \frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right\rangle - g(x_{n}) - \left\langle u, \frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right\rangle \right]$$

$$\leq \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right) - \left\langle u, \frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right\rangle \right]$$

$$= \frac{\eta}{1+\eta} \lambda_{n} \beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_{n}} \right) \right] \quad \forall n \geq 1.$$

By combining these two inequalities with (12), it follows for every $n \ge 1$ that

$$\begin{split} \varphi_{n+1} &- \varphi_n - \alpha (\varphi_n - \varphi_{n-1}) + \lambda_n \beta_n \left[\frac{2}{L_g(1+\eta)} - (1+\eta) \lambda_n \beta_n \right] \| \nabla g(x_n) \|^2 \\ &+ \frac{\eta}{1+\eta} \lambda_n \beta_n g(x_n) \leq 2\alpha \|x_n - x_{n-1}\|^2 \\ &+ \left[\frac{1}{1+\eta} + \frac{\eta}{2(1+\eta)} + \alpha - 1 \right] \|x_{n+1} - x_n\|^2 \\ &+ \frac{4(1+\eta)}{\eta} \lambda_n^2 \| \nabla h(u) + v \|^2 \\ &+ \lambda_n \left[\frac{4(1+\eta)}{\eta} \lambda_n - \frac{2}{L_h} \right] \| \nabla h(x_n) - \nabla h(u) \|^2 \\ &+ \frac{\eta}{1+\eta} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta}{1+\eta} \beta_n} \right) \right]. \end{split}$$

Since $\alpha \in [0, 1)$ and $\eta > 0$, it holds that $\frac{1}{1+\eta} + \frac{\eta}{2(1+\eta)} + \alpha - 1 < 1$, which together with the inequality above lead to the conclusion.

For simplicity, we will make use of the following notation:

$$\Omega_n(x_n) := f(x_n) + h(x_n) + \beta_n g(x_n) \quad \forall n \ge 1.$$

Lemma 2 For every $n \ge 1$ it holds that

$$\Omega_{n+1}(x_{n+1}) - \Omega_n(x_n) \le \left[\frac{\alpha}{2\lambda_n} - \frac{1}{\lambda_n} + \frac{L_h + \beta_n L_g}{2} \right] \|x_{n+1} - x_n\|^2 + \frac{\alpha}{2\lambda_n} \|x_n - x_{n-1}\|^2 + (\beta_{n+1} - \beta_n)g(x_{n+1}).$$
(13)



Proof Recall that for every $n \ge 1$ we have $\frac{y_n - x_{n+1}}{\lambda_n} - \nabla h(x_n) - \beta_n g(x_n) \in \partial f(x_{n+1})$, which implies

$$f(x_n) \ge f(x_{n+1}) + \left(\frac{y_n - x_{n+1}}{\lambda_n} - \nabla h(x_n) - \beta_n g(x_n), x_n - x_{n+1}\right).$$

From here, it follows that for every n > 1 we have

$$f(x_{n+1}) - f(x_n) \leq -\frac{1}{\lambda_n} \|x_{n+1} - x_n\|^2 + \frac{\alpha}{\lambda_n} \langle x_n - x_{n-1}, x_{n+1} - x_n \rangle + \langle \nabla h(x_n), x_n - x_{n+1} \rangle + \beta_n \langle \nabla g(x_n), x_n - x_{n+1} \rangle \leq \left[\frac{\alpha}{2\lambda_n} - \frac{1}{\lambda_n} \right] \|x_{n+1} - x_n\|^2 + \frac{\alpha}{2\lambda_n} \|x_n - x_{n-1}\|^2 + \langle \nabla h(x_n), x_n - x_{n+1} \rangle + \beta_n \langle \nabla g(x_n), x_n - x_{n+1} \rangle.$$
(14)

From the Descent Lemma (see for example [12, Theorem 18.15]), we obtain for every $n \ge 1$ that

$$g(x_{n+1}) \le g(x_n) + \langle \nabla g(x_n), x_{n+1} - x_n \rangle + \frac{L_g}{2} ||x_{n+1} - x_n||^2,$$

and

$$h(x_{n+1}) \le h(x_n) + \langle \nabla h(x_n), x_{n+1} - x_n \rangle + \frac{L_h}{2} ||x_{n+1} - x_n||^2.$$

By combining these relations with inequality (14), we finally obtain the inequality in the statement of the lemma.

For the forthcoming statements, we fix an element $u \in S$. For a simpler formulation of these results, we will use the following notation:

$$\Gamma_n := \Omega_n(x_n) - K \frac{\eta_0}{1 + \eta_0} \lambda_n \beta_n g(x_n) + K \varphi_n$$

$$= f(x_n) + h(x_n) + \left(1 - K \frac{\eta_0}{1 + \eta_0} \lambda_n\right) \beta_n g(x_n) + K \varphi_n \quad \forall n \ge 1.$$

Lemma 3 Let $u \in S$. According to the first-order optimality conditions, there exist $v \in \partial f(u)$ and $p \in N_{\arg\min g}(u)$, such that $0 = v + \nabla h(u) + p$. Then, for every $n \ge 2$, it holds that

$$\Gamma_{n+1} - \Gamma_{n} - \alpha(\Gamma_{n} - \Gamma_{n-1}) + K\lambda_{n}\beta_{n} \left[\frac{2}{L_{g}(1+\eta_{0})} - (1+\eta_{0})\lambda_{n}\beta_{n} \right] \|\nabla g(x_{n})\|^{2} \\
\leq \left[\frac{\alpha}{2\lambda_{n}} - \frac{1}{\lambda_{n}} + \frac{L_{h} + \beta_{n}L_{g}}{2} + K \right] \|x_{n+1} - x_{n}\|^{2} \\
+ \left[\frac{\alpha}{2\lambda_{n}} + 2\alpha K \right] \|x_{n} - x_{n-1}\|^{2} + \frac{4K(1+\eta_{0})}{\eta_{0}}\lambda_{n}^{2} \|\nabla h(u) + v\|^{2} \\
+ K \left[\frac{4(1+\eta_{0})}{\eta_{0}}\lambda_{n}^{2} - \frac{2\lambda_{n}}{L_{h}} \right] \|\nabla h(x_{n}) - \nabla h(u)\|^{2} \\
+ \frac{K\eta_{0}}{1+\eta_{0}}\lambda_{n}\beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta_{0}}{1+\eta_{0}}\beta_{n}} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_{0}}{1+\eta_{0}}\beta_{n}} \right) \right] \\
+ \alpha(\Omega_{n-1}(x_{n-1}) - \Omega_{n}(x_{n})) + \frac{\alpha K\eta_{0}}{1+\eta_{0}} (\lambda_{n}\beta_{n}g(x_{n}) - \lambda_{n-1}\beta_{n-1}g(x_{n-1})). \tag{15}$$





Proof We write (2) for $\eta := \eta_0$, multiply it by K, and after combining the resulting inequality with (13), we obtain for every $n \ge 1$ that

$$\begin{split} &\Omega_{n+1}(x_{n+1}) + K\varphi_{n+1} - \Omega_{n}(x_{n}) - K\varphi_{n} + \frac{K\eta_{0}}{1+\eta_{0}}\lambda_{n}\beta_{n}g(x_{n}) \\ &-\alpha(K\varphi_{n} - K\varphi_{n-1}) + K\lambda_{n}\beta_{n}\left[\frac{2}{L_{g}(1+\eta_{0})} - (1+\eta_{0})\lambda_{n}\beta_{n}\right]\|\nabla g(x_{n})\|^{2} \\ &\leq \left[\frac{\alpha}{2\lambda_{n}} - \frac{1}{\lambda_{n}} + \frac{L_{h} + \beta_{n}L_{g}}{2} + K\right]\|x_{n+1} - x_{n}\|^{2} + \left[\frac{\alpha}{2\lambda_{n}} + 2\alpha K\right]\|x_{n} - x_{n-1}\|^{2} \\ &+ \frac{4K(1+\eta_{0})}{\eta_{0}}\lambda_{n}^{2}\|\nabla h(u) + v\|^{2} + K\left[\frac{4(1+\eta_{0})}{\eta_{0}}\lambda_{n}^{2} - \frac{2\lambda_{n}}{L_{h}}\right]\|\nabla h(x_{n}) - \nabla h(u)\|^{2} \\ &+ (\beta_{n+1} - \beta_{n})g(x_{n+1}) + \frac{K\eta_{0}}{1+\eta_{0}}\lambda_{n}\beta_{n}\left[g^{*}\left(\frac{2p}{\frac{\eta_{0}}{1+\eta_{0}}\beta_{n}}\right) - \sigma_{\arg\min g}\left(\frac{2p}{\frac{\eta_{0}}{1+\eta_{0}}\beta_{n}}\right)\right]. \end{split}$$

In view of Assumption 1(III), we deduce that

$$\begin{split} &\Omega_{n+1}(x_{n+1}) + K\varphi_{n+1} - \Omega_{n}(x_{n}) - K\varphi_{n} + \frac{K\eta_{0}}{1 + \eta_{0}} \lambda_{n}\beta_{n}g(x_{n}) \\ &- \alpha(K\varphi_{n} - K\varphi_{n-1}) + K\lambda_{n}\beta_{n} \left[\frac{2}{L_{g}(1 + \eta_{0})} - (1 + \eta_{0})\lambda_{n}\beta_{n} \right] \|\nabla g(x_{n})\|^{2} \\ &\leq \left[\frac{\alpha}{2\lambda_{n}} - \frac{1}{\lambda_{n}} + \frac{L_{h} + \beta_{n}L_{g}}{2} + K \right] \|x_{n+1} - x_{n}\|^{2} + \left[\frac{\alpha}{2\lambda_{n}} + 2\alpha K \right] \|x_{n} - x_{n-1}\|^{2} \\ &+ \frac{4K(1 + \eta_{0})}{\eta_{0}} \lambda_{n}^{2} \|\nabla h(u) + v\|^{2} + K \left[\frac{4(1 + \eta_{0})}{\eta_{0}} \lambda_{n}^{2} - \frac{2\lambda_{n}}{L_{h}} \right] \|\nabla h(x_{n}) - \nabla h(u)\|^{2} \\ &+ \frac{K\eta_{0}}{1 + \eta_{0}} \lambda_{n+1} \beta_{n+1} g(x_{n+1}) \\ &+ \frac{K\eta_{0}}{1 + \eta_{0}} \lambda_{n} \beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta_{0}}{1 + \eta_{0}}} \beta_{n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_{0}}{1 + \eta_{0}}} \beta_{n} \right) \right] \quad \forall n \geq 1 \end{split}$$

and further

$$\begin{split} & \Gamma_{n+1} - \Gamma_n - \alpha (K\varphi_n - K\varphi_{n-1}) \\ & + K\lambda_n \beta_n \left[\frac{2}{L_g(1 + \eta_0)} - (1 + \eta_0)\lambda_n \beta_n \right] \|\nabla g(x_n)\|^2 \\ & \leq \left[\frac{\alpha}{2\lambda_n} - \frac{1}{\lambda_n} + \frac{L_h + \beta_n L_g}{2} + K \right] \|x_{n+1} - x_n\|^2 + \left[\frac{\alpha}{2\lambda_n} + 2\alpha K \right] \|x_n - x_{n-1}\|^2 \\ & + \frac{4K(1 + \eta_0)}{\eta_0} \lambda_n^2 \|\nabla h(u) + v\|^2 + K \left[\frac{4(1 + \eta_0)}{\eta_0} \lambda_n^2 - \frac{2\lambda_n}{L_h} \right] \|\nabla h(x_n) - \nabla h(u)\|^2 \\ & + \frac{K\eta_0}{1 + \eta_0} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) \right] \quad \forall n \geq 2. \end{split}$$

In order to obtain (15), we only have to add $\alpha(\Omega_{n-1}(x_{n-1}) - \Omega_n(x_n))$ and $\frac{\alpha K \eta_0}{1+\eta_0}(\lambda_n \beta_n g(x_n) - \lambda_{n-1} \beta_{n-1} g(x_{n-1}))$ to both sides of the above inequality.



The following results is a very useful tool in the convergence analysis of inertial algorithms (see [1, 2, 20]).

Lemma 4 Let $\{a_n\}_{n=0}^{\infty}$, $\{b_n\}_{n=1}^{\infty}$ and $\{c_n\}_{n=1}^{\infty}$ be real sequences and $\alpha \in [0, 1)$ be a given real number. Assume that $\{a_n\}_{n=1}^{\infty}$ is bounded from below, $\{b_n\}_{n=1}^{\infty}$ is nonnegative and $\sum_{n=1}^{\infty} c_n < +\infty$, such that

$$a_{n+1} - a_n - \alpha(a_n - a_{n-1}) + b_n \le c_n \quad \forall n \ge 1.$$

Then the following statements hold:

- (i) $\sum_{n=1}^{\infty} [a_n a_{n-1}]_+ < +\infty$, where $[t]_+ := \max\{t, 0\}$; (ii) $\{a_n\}_{n=1}^{\infty}$ converges and $\sum_{n=1}^{\infty} b_n < +\infty$.

The results presented in Lemma 5 related to the convergence of the generated iterates and in Lemma 6 related to the convergence of the objective function values will be used in the next section in the proof of the main theorem in combination with the Opial lemma stated in Lemma 7.

Lemma 5 Let $u \in S$. According to the first-order optimality conditions there exist $v \in S$. $\partial f(u)$ and $p \in N_{\arg\min g}(u)$, such that $0 = v + \nabla h(u) + p$. Then the following statements are true:

- (i) The sequence $\{\Gamma_n\}_{n=1}^{+\infty}$ is bounded from below; (ii) $\sum_{n=1}^{\infty} \|x_{n+1} x_n\|^2 < +\infty$; (iii) $\lim_{n \to +\infty} \Gamma_n$ exists and $\sum_{n=1}^{+\infty} \lambda_n \beta_n \|\nabla g(x_n)\|^2 < +\infty$; (iv) $\lim_{n \to +\infty} \|x_n u\|$ exists, $\sum_{n=1}^{\infty} [\varphi_n \varphi_{n-1}]_+ < +\infty$ and $\sum_{n=1}^{\infty} \lambda_n \beta_n g(x_n) < +\infty$;
- (v) $\lim_{n\to+\infty} \Omega_n(x_n)$ exists;
- (vi) $\lim_{n\to+\infty} g(x_n) = 0$ and every sequential weak cluster point of $\{x_n\}_{n=1}^{\infty}$ lies in arg min g.

Proof (i) According to Assumption 1(III) we have that

$$\frac{L_h + \beta_n L_g}{2} + \frac{\alpha - 1}{\lambda_n} \le -(1 + 2\alpha)K - c,$$

which implies that $1 \ge K \lambda_n$ and further

$$\left(1 - \frac{K\eta_0}{1 + \eta_0} \lambda_n\right) \beta_n g(x_n) \ge 0 \quad \forall n \ge 1.$$
(16)

By using the definition of Γ_n and Assumption 1(II), we easily derive that $\{\Gamma_n\}_{n=1}^{\infty}$ is bounded from below.

(ii) For every $n \geq 2$, we set

$$\mu_n := \Gamma_n - \alpha \Gamma_{n-1} + \left(\frac{1}{2\lambda_n} + 2K\right) \alpha \|x_n - x_{n-1}\|^2$$

and

$$\omega_n := \alpha(\Omega_{n-1}(x_{n-1}) - \Omega_n(x_n)) + \frac{\alpha K \eta_0}{1 + \eta_0} (\lambda_n \beta_n g(x_n) - \lambda_{n-1} \beta_{n-1} g(x_{n-1})).$$



For a fixed natural number $N_0 \ge 2$, it holds that

$$\frac{1}{\alpha} \sum_{n=2}^{N_0} \omega_n = f(x_1) + h(x_1) + \left(1 - \frac{K\eta_0}{1 + \eta_0} \lambda_1\right) \beta_1 g(x_1) - f(x_{N_0}) - h(x_{N_0}) \\
- \left(1 - \frac{K\eta_0}{1 + \eta_0} \lambda_{N_0}\right) \beta_{N_0} g(x_{N_0}).$$

Since f + h is bounded from below and relation (16) is true, we obtain that $\{\omega_n\}_{n=1}^{\infty}$ is summable.

For every $n \ge 1$, we set

$$\delta_n := \left(\frac{1}{2\lambda_n} + 2K\right)\alpha + c.$$

Consequently, according Assumption 1(III), it follows that

$$\frac{L_h + \beta_n L_g}{2} + \frac{\alpha}{2\lambda_n} - \frac{1}{\lambda_n} + K \le -\delta_n \quad \forall n \ge 1.$$
 (17)

Further, for every $n \ge 1$, it holds

$$-\delta_n + \alpha \left(\frac{1}{2\lambda_{n+1}} + 2K \right) = \frac{\alpha}{2} \left(\frac{1}{\lambda_{n+1}} - \frac{1}{\lambda_n} \right) - c,$$

which, together with Assumption 1(IV), implies that

$$-\delta_n + \alpha \left(\frac{1}{2\lambda_{n+1}} + 2K\right) \le 1 - c \tag{18}$$

and so

$$\delta_{n+1} \le \delta_n + 1. \tag{19}$$

On the other hand, by Assumption 1(III), we also have for every $n \ge 1$

$$0 < \frac{2}{L_{\varrho}(1+\eta_0)} - (1+\eta_0)b \le \frac{2}{L_{\varrho}(1+\eta_0)} - (1+\eta_0)\lambda_n\beta_n \tag{20}$$

and so

$$K\lambda_n\beta_n\left[\frac{2}{L_g(1+\eta_0)}-(1+\eta_0)\lambda_n\beta_n\right]\geq 0.$$

By employing the last inequality in Lemma 3 we obtain for every $n \ge 2$

$$\begin{split} \mu_{n+1} - \mu_n &= \Gamma_{n+1} - \Gamma_n - \alpha \left(\Gamma_n - \Gamma_{n-1} \right) + \alpha \left(\frac{1}{2\lambda_{n+1}} + 2K \right) \|x_{n+1} - x_n\|^2 \\ &- \alpha \left(\frac{1}{2\lambda_n} + 2K \right) \|x_n - x_{n-1}\|^2 \\ &\leq \left[\frac{\alpha}{2\lambda_n} - \frac{1}{\lambda_n} + \frac{L_h + \beta_n L_g}{2} + K + \alpha \left(\frac{1}{2\lambda_{n+1}} + 2K \right) \right] \|x_{n+1} - x_n\|^2 \\ &+ \frac{4K(1 + \eta_0)}{\eta_0} \lambda_n^2 \|\nabla h(u) + v\|^2 \\ &+ K \left[\frac{4(1 + \eta_0)}{\eta_0} \lambda_n^2 - \frac{2\lambda_n}{L_h} \right] \|\nabla h(x_n) - \nabla h(u)\|^2 \\ &+ \frac{K\eta_0}{1 + \eta_0} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) \right] + \omega_n \\ &\leq (1 - c) \|x_{n+1} - x_n\|^2 + \frac{4K(1 + \eta_0)}{\eta_0} \lambda_n^2 \|\nabla h(u) + v\|^2 \\ &+ K \left[\frac{4(1 + \eta_0)}{\eta_0} \lambda_n^2 - \frac{2\lambda_n}{L_h} \right] \|\nabla h(x_n) - \nabla h(u)\|^2 \\ &+ \frac{K\eta_0}{1 + \eta_0} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) \right] + \omega_n, \end{split}$$

where for the last inequality we use (17) and (18). Since $\lambda_n \to 0$ as $n \to +\infty$, there exists $N_1 \in \mathbb{N}$, such that for every $n \ge N_1$, we have $\frac{4(1+\eta_0)}{\eta_0}\lambda_n - \frac{2}{L_h} < 0$. This implies that for every $n \ge N_1$

$$\mu_{n+1} - \mu_n \leq (1 - c) \|x_{n+1} - x_n\|^2 + \frac{4K(1 + \eta_0)}{\eta_0} \lambda_n^2 \|\nabla h(u) + v\|^2 + \frac{K\eta_0}{1 + \eta_0} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) \right] + \omega_n.$$

Summing up this inequality for $n = N_1, ..., N_2$, where N_2 is a natural number with $N_2 \ge N_1$, we obtain that

$$\mu_{N_{2}+1} - \mu_{N_{1}} \leq (1 - c) \sum_{n=N_{1}}^{N_{2}} \|x_{n+1} - x_{n}\|^{2} + \frac{4K(1 + \eta_{0})}{\eta_{0}} \|\nabla h(u) + v\|^{2} \sum_{n=N_{1}}^{N_{2}} \lambda_{n}^{2} + \frac{K\eta_{0}}{1 + \eta_{0}} \sum_{n=N_{1}}^{N_{2}} \lambda_{n} \beta_{n} \left[g^{*} \left(\frac{2p}{\frac{\eta_{0}}{1 + \eta_{0}} \beta_{n}} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_{0}}{1 + \eta_{0}} \beta_{n}} \right) \right] + \sum_{n=N_{1}}^{N_{2}} \omega_{n}.$$

$$(21)$$



This means that $\{\mu_n\}_{n=2}^{\infty}$ is bounded from above (we take into account that c > 1). Let M be a positive upper bound of $\{\mu_n\}_{n=2}^{\infty}$. Observing that $\Gamma_{n+1} - \alpha \Gamma_n \leq \mu_{n+1} \leq M$, thus $\Gamma_{n+1} \leq \alpha \Gamma_n + M$ for every $n \geq N_1$, we obtain

$$\Gamma_n \le \alpha^{n-N_1} \Gamma_{N_1} + M \sum_{k=1}^{n-N_1} \alpha^{k-1} \le \alpha^{n-N_1} \Gamma_{N_1} + \frac{M}{1-\alpha} \quad \forall n \ge N_1 + 1.$$

Since $\{\Gamma_n\}_{n=1}^{\infty}$ is bounded from below, there exists $C \in \mathbb{R}$, such that

$$-\mu_{N_2+1} = -\Gamma_{N_2+1} + \alpha \Gamma_{N_2} - \left(\frac{1}{2\lambda_{N_2+1}} + 2K\right) \alpha \|x_{N_2+1} - x_{N_2}\|^2$$

$$\leq \alpha \Gamma_{N_2} + C \leq \alpha^{N_2-N_1+1} \Gamma_{N_1} + \frac{M\alpha}{1-\alpha} + C \quad \forall N_2 \geq N_1.$$

Thus, from the inequality (21), by taking into account that c > 1, we deduce that

$$\sum_{n=1}^{+\infty} \|x_{n+1} - x_n\|^2 < +\infty.$$

(iii) From Lemma 3, by using (17), (19), and (20), we obtain

$$\Gamma_{n+1} - \Gamma_n - \alpha (\Gamma_n - \Gamma_{n-1}) + K \lambda_n \beta_n \left[\frac{2}{L_g (1 + \eta_0)} - (1 + \eta_0) b \right] \|\nabla g(x_n)\|^2 \\
\leq -\delta_n \|x_{n+1} - x_n\|^2 + \delta_{n-1} \|x_n - x_{n-1}\|^2 + \frac{4K (1 + \eta_0)}{\eta_0} \lambda_n^2 \|\nabla h(u) + v\|^2 \\
+ \frac{K \eta_0}{1 + \eta_0} \lambda_n \beta_n \left[g^* \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) - \sigma_{\arg\min g} \left(\frac{2p}{\frac{\eta_0}{1 + \eta_0} \beta_n} \right) \right] + \omega_n \quad \forall n \geq N_1.$$

Since $\{\Gamma_n\}_{n=1}^{\infty}$ is bounded from below, by using Lemma 4, it follows that (iii) is true.

- (iv) The statement follows from Lemma 1 and Lemma 4.
- (v) Thanks to (iii), (iv) and $\Gamma_n = \Omega_n(x_n) K \frac{\eta_0}{1+\eta_0} \lambda_n \beta_n g(x_n) + K \varphi_n$ for every $n \ge 1$, we obtain that $\lim_{n \to +\infty} \Omega_n(x_n)$ exists.
- (vi) Since $\lambda_n \beta_n \ge a > 0$ for every $n \ge 1$, we have $\sum_{n=1}^{+\infty} g(x_n) < +\infty$ and so $\lim_{n \to +\infty} g(x_n) = 0$.

Finally, let $y \in \mathcal{H}$ be a sequential weak cluster point of $\{x_n\}_{n=1}^{\infty}$ and $\{x_{n_j}\}_{j=1}^{\infty}$ be a subsequence of $\{x_n\}_{n=1}^{\infty}$, such that x_{n_j} weakly converges to y as $j \to +\infty$. Since g is weakly lower semicontinuous, we obtain that

$$g(y) \le \liminf_{j \to +\infty} g(x_{n_j}) \le \lim_{n \to +\infty} g(x_n) = 0,$$

which means that $y \in \arg \min g$.

Lemma 6 *Let* $u \in S$. *Then, we have*

$$-\infty \le \sum_{n=1}^{\infty} \lambda_n \left[\Omega_{n+1}(x_{n+1}) - (f(u) + h(u)) \right] < +\infty.$$



Proof For every n > 1, we have that

$$\begin{split} \Omega_{n+1}(x_{n+1}) - (f(u) + h(u)) &= f(x_{n+1}) + h(x_n) + \beta_n g(x_n) - (f(u) + h(u)) \\ &+ (h(x_{n+1}) - h(x_n)) + (\beta_{n+1} - \beta_n) g(x_{n+1}) \\ &+ \beta_n (g(x_{n+1}) - g(x_n)) \\ &\leq f(x_{n+1}) + h(x_n) + \beta_n g(x_n) - (f(u) + h(u)) \\ &+ (h(x_{n+1}) - h(x_n)) + \frac{K\eta_0}{1 + \eta_0} \lambda_{n+1} \beta_{n+1} g(x_{n+1}) \\ &+ \beta_n (g(x_{n+1}) - g(x_n)) \end{split}$$

and so

$$\lambda_{n}[\Omega_{n+1}(x_{n+1}) - (f(u) + h(u))] \leq \lambda_{n}[f(x_{n+1}) + h(x_{n}) + \beta_{n}g(x_{n}) - (f(u) + h(u))]$$

$$+ \lambda_{n}[(h(x_{n+1}) - h(x_{n})]$$

$$+ \frac{K\eta_{0}}{1 + \eta_{0}} \lambda_{n}\lambda_{n+1}\beta_{n+1}g(x_{n+1})$$

$$+ \lambda_{n}\beta_{n}[g(x_{n+1}) - g(x_{n})].$$

According to the Descent Lemma we have for every $n \ge 1$

$$\lambda_{n}[h(x_{n+1}) - h(x_{n})] \leq \lambda_{n} \langle \nabla h(x_{n}), x_{n+1} - x_{n} \rangle + \frac{\lambda_{n} L_{h}}{2} \|x_{n+1} - x_{n}\|^{2}$$

$$\leq \frac{\lambda_{n}^{2}}{2} \|\nabla h(x_{n})\|^{2} + \frac{1 + \lambda_{n} L_{h}}{2} \|x_{n+1} - x_{n}\|^{2}$$

and

$$\lambda_{n}\beta_{n}[g(x_{n+1}) - g(x_{n})] \leq \lambda_{n}\beta_{n}\langle\nabla g(x_{n}), x_{n+1} - x_{n}\rangle + \frac{\lambda_{n}\beta_{n}L_{g}}{2}\|x_{n+1} - x_{n}\|^{2}$$

$$\leq \frac{\lambda_{n}^{2}\beta_{n}^{2}}{2}\|\nabla g(x_{n})\|^{2} + \frac{1 + \lambda_{n}\beta_{n}L_{g}}{2}\|x_{n+1} - x_{n}\|^{2},$$

which give rise to the following estimate

$$\lambda_{n}[\Omega_{n+1}(x_{n+1}) - (f(u) + h(u))] \leq \lambda_{n}[f(x_{n+1}) + h(x_{n}) + \beta_{n}g(x_{n}) - (f(u) + h(u))] + \frac{\lambda_{n}^{2}}{2} \|\nabla h(x_{n})\|^{2} + \frac{2 + \lambda_{n}(L_{h} + \beta_{n}L_{g})}{2} \|x_{n+1} - x_{n}\|^{2} + \frac{K\eta_{0}}{1 + \eta_{0}} \lambda_{n}\lambda_{n+1}\beta_{n+1}g(x_{n+1}) + \frac{\lambda_{n}^{2}\beta_{n}^{2}}{2} \|\nabla g(x_{n})\|^{2} \quad \forall n \geq 1.$$
 (22)

Further, we notice that for every $n \ge 1$

$$f(x_{n+1}) - f(u) \le \left(\frac{y_n - x_{n+1}}{\lambda_n} - \nabla h(x_n) - \beta_n \nabla g(x_n), x_{n+1} - u\right)$$

or, equivalently,

$$\left\langle \frac{y_n - x_{n+1}}{\lambda_n}, u - x_{n+1} \right\rangle - \left\langle \nabla h(x_n), u - x_{n+1} \right\rangle - \beta_n \left\langle \nabla g(x_n), u - x_{n+1} \right\rangle$$

$$\leq f(u) - f(x_{n+1}). \tag{23}$$



On the other hand, since g(u) = 0, we have for every $n \ge 1$

$$0 = g(u) > g(x_n) + \langle \nabla g(x_n), u - x_n \rangle$$

or, equivalently,

$$-\beta_n \langle \nabla g(x_n), u - x_{n+1} \rangle \ge \beta_n g(x_n) + \beta_n \langle \nabla g(x_n), x_{n+1} - x_n \rangle. \tag{24}$$

Similarly, we have for every $n \ge 1$

$$h(u) > h(x_n) + \langle \nabla h(x_n), u - x_n \rangle$$

which implies that

$$-\langle \nabla h(x_n), u - x_{n+1} \rangle > h(x_n) - h(u) + \langle \nabla h(x_n), x_{n+1} - x_n \rangle. \tag{25}$$

By summing up the inequalities in (23)–(25), we obtain for every $n \ge 1$

$$2\lambda_{n}[f(x_{n+1}) + h(x_{n}) + \beta_{n}g(x_{n}) - (f(u) + h(u))] \leq 2\langle y_{n} - x_{n+1}, x_{n+1} - u \rangle + 2\lambda_{n}\beta_{n}\langle \nabla g(x_{n}), x_{n} - x_{n+1} \rangle + 2\lambda_{n}\langle \nabla h(x_{n}), x_{n} - x_{n+1} \rangle \leq 2\langle y_{n} - x_{n+1}, x_{n+1} - u \rangle + \lambda_{n}^{2}\beta_{n}^{2} \|\nabla g(x_{n})\|^{2} + 2\|x_{n} - x_{n+1}\|^{2} + \lambda_{n}^{2} \|\nabla h(x_{n})\|^{2}.$$
(26)

Not least, according to (4) and (5), we obtain for every $n \ge 1$

$$2\langle y_{n} - x_{n+1}, x_{n+1} - u \rangle = 2\langle x_{n} - x_{n+1}, x_{n+1} - u \rangle + 2\alpha \langle x_{n} - x_{n-1}, x_{n+1} - u \rangle$$

$$\leq \varphi_{n} - \varphi_{n+1} + \alpha(\varphi_{n} - \varphi_{n-1})$$

$$+ 2\alpha \|x_{n} - x_{n-1}\|^{2} + (\alpha - 1) \|x_{n+1} - x_{n}\|^{2}$$

$$\leq \varphi_{n} - \varphi_{n+1} + \alpha(\varphi_{n} - \varphi_{n-1}) + 2\alpha \|x_{n} - x_{n-1}\|^{2},$$

which, combined with (26) and Lemma 5(iv), implies that

$$\sum_{n=1}^{\infty} \lambda_n [f(x_{n+1}) + h(x_n) + \beta_n g(x_n) - (f(u) + h(u))] < +\infty.$$

The conclusion follows by taking into account (22).

3 Convergence of the Iterates and of the Objective Function Values

In this section, we will prove the main result of this paper. This addresses the convergence of both the sequence of iterates $\{x_n\}_{n=1}^{\infty}$ generated by Algorithm 1 and of the sequence of objective values $\{f(x_n) + h(x_n)\}_{n=1}^{\infty}$.

The Opial lemma, which we state next and for which we refer to [12, Lemma 2.39], will play a crucial role in the convergence analysis.

Lemma 7 Let \mathcal{H} be a real Hilbert space, $C \subseteq \mathcal{H}$ a nonempty set and $\{x_n\}_{n=1}^{\infty}$ a given sequence, such that:

- (i) For every $z \in C$, $\lim_{n \to +\infty} ||x_n z||$ exists.
- (ii) Every sequential weak cluster point of $\{x_n\}_{n=1}^{\infty}$ lies in C.

Then, the sequence $\{x_n\}_{n=1}^{\infty}$ converges weakly to a point in C.



Theorem 1 Let $\{x_n\}_{n=1}^{\infty}$ be the sequence generated by Algorithm 1. Then:

- (i) the sequence $\{x_n\}_{n=1}^{\infty}$ converges weakly to a point in S;
- (ii) the sequence $\{f(x_n) + h(x_n)\}_{n=1}^{\infty}$ converges to the optimal objective value of the optimization problem (1).

Proof (i) We know that $\lim_{n\to+\infty} \|x_n - u\|$ exists for all $u \in \mathcal{S}$ (see Lemma 5(iv)); hence, in view of the Opial lemma, it is sufficient to show that all sequential weak cluster points of $\{x_n\}_{n=1}^{\infty}$ are in \mathcal{S} . Since $\{\lambda_n\}_{n=1}^{\infty} \notin \ell^1$ and $\lim_{n\to+\infty} \Omega_n(x_n)$ exists, from Lemma 6, we obtain that

$$\lim_{n \to +\infty} \Omega_n(x_n) \le f(u) + h(u) \quad \forall u \in \mathcal{S}.$$

Let $x^* \in \mathcal{H}$ be a sequential weak cluster point of $\{x_n\}_{n=1}^{\infty}$ and $\{x_{n_k}\}_{k=1}^{\infty}$ be a subsequence of $\{x_n\}_{n=1}^{\infty}$, such that x_{n_k} converges weakly to x^* as $k \to +\infty$. From here, by Lemma 5(vi), we obtain that $x^* \in \arg \min g$. Take an arbitrary $u \in \mathcal{S}$. The weak lower semicontinuity of f and h implies that

$$f(x^*) + h(x^*) \leq \liminf_{k \to +\infty} f(x_{n_k}) + \liminf_{k \to +\infty} h(x_{n_k})$$

$$\leq \liminf_{k \to +\infty} \left[f(x_{n_k}) + h(x_{n_k}) \right]$$

$$\leq \lim_{n \to +\infty} \Omega_n(x_n) \leq f(u) + h(u)$$

$$= \min\{ f(x) + h(x) : x \in \arg \min g \}$$

which means that $x^* \in \mathcal{S}$.

(ii) The statement is a direct consequence of the above inequalities.

We close the paper by a remark which discusses the fulfillment of the conditions stated in Assumption 1.

Remark 2 We chose

$$\eta_0 \in (0, +\infty), \quad c \in (1, +\infty), \quad q \in \left(\frac{1}{2}, 1\right), \quad \alpha \in \left(0, 1 - \frac{1}{2(1 + \eta_0)^2}\right)$$

and

$$\gamma \in \left(\frac{1}{L_g(1-\alpha)(1+\eta_0)^2}, \min\left\{\frac{2}{L_g}, \frac{3}{L_g(1-\alpha)(1+\eta_0)^2}\right\}\right).$$

We set

$$K:=\frac{2(1+\eta_0)}{\alpha\eta_0},$$

$$\beta_n := \frac{\gamma \left[L_h + 2((1+2\alpha)K + c) \right]}{2 - \gamma L_g} + \left[\frac{(1-\alpha)\gamma L_g (1+\eta_0)^2 - 1}{L_g (1+\eta_0)^2} \right] \frac{K\eta_0}{1+\eta_0} n^q,$$

and

$$\lambda_n := \frac{(1-\alpha)\gamma}{\beta_n} - \frac{1}{\beta_n L_{\varrho}(1+\eta_0)^2}$$

for every $n \ge 1$.



(i) By taking $a:=(1-\alpha)\gamma-\frac{1}{L_g(1+\eta_0)^2}$ and b>0, such that $a< b<\frac{2}{L_g(1+\eta_0)^2}$, we have

$$0 < a = \lambda_n \beta_n < b < \frac{2}{L_g (1 + \eta_0)^2} \quad \forall n \ge 1.$$

- (ii) Since $\beta_n \geq \frac{\gamma[L_h+2((1+2\alpha)K+c)]}{2-\gamma L_g}$, we have $\frac{L_h+\beta_nL_g}{2} \frac{\beta_n}{\gamma} \leq -(1+2\alpha)K c$ for every $n \geq 1$. On the other hand, since $\frac{\beta_n}{\gamma} \leq \frac{(1-\alpha)}{\lambda_n}$, we have that $\frac{L_h+\beta_nL_g}{2} + \frac{\alpha-1}{\lambda_n} \leq -(1+2\alpha)K c$ for every $n \geq 1$.
- (iii) For every $n \ge 1$, we also have

$$\beta_{n+1} - \beta_n = \left[\frac{(1-\alpha)\gamma L_g (1+\eta_0)^2 - 1}{L_g (1+\eta_0)^2} \right] \frac{K\eta_0}{1+\eta_0} \left((n+1)^q - n^q \right)$$

$$\leq \left[\frac{(1-\alpha)\gamma L_g (1+\eta_0)^2 - 1}{L_g (1+\eta_0)^2} \right] \frac{K\eta_0}{1+\eta_0}$$

$$= \frac{K\eta_0}{1+\eta_0} \lambda_{n+1} \beta_{n+1}.$$

(iv) From (iii), it follows that for every $n \ge 1$

$$\frac{1}{\lambda_{n+1}} - \frac{1}{\lambda_n} = (\beta_{n+1} - \beta_n) \left[\frac{L_g (1 + \eta_0)^2}{(1 - \alpha) \gamma L_g (1 + \eta_0)^2 - 1} \right] \le \frac{K \eta_0}{1 + \eta_0} = \frac{2}{\alpha}.$$

- (v) Due to the fact that $q \in \left(\frac{1}{2}, 1\right)$, we have $\sum_{n=1}^{+\infty} \frac{1}{\beta_n} = +\infty$ and $\sum_{n=1}^{+\infty} \frac{1}{\beta_n^2} < +\infty$. Consequently, $\{\lambda_n\}_{n=1}^{\infty} \in \ell^2 \setminus \ell^1$.
- (vi) Since $g \le \delta_{\arg\min g}$, it holds that $g^* \ge (\delta_{\arg\min g})^* = \sigma_{\arg\min g}$ and so $g^* \sigma_{\arg\min g} \ge 0$. For a function $g : \mathcal{H} \to \mathbb{R}$ fulfilling $g \ge \frac{a}{2} \mathrm{dist}^2(\cdot, \arg\min g)$ where a > 0, it holds that $g^*(x) \sigma_{\arg\min g}(x) \le \frac{1}{2a} \|x\|^2$ for every $x \in \mathcal{H}$. Thus, for every $n \ge 1$,

$$\lambda_n \beta_n \left[g^* \left(\frac{p}{\beta_n} \right) - \sigma_{\arg\min g} \left(\frac{p}{\beta_n} \right) \right] \le \frac{\lambda_n}{2a\beta_n} \|p\|^2 \quad \forall p \in \operatorname{ran}(N_{\arg\min g}).$$

Since $\sum_{n=1}^{\infty} \frac{1}{\beta_n^2} < +\infty$, from here it follows that

$$\sum_{n=1}^{\infty} \lambda_n \beta_n \left[g^* \left(\frac{p}{\beta_n} \right) - \sigma_{\arg \min g} \left(\frac{p}{\beta_n} \right) \right] < +\infty.$$

4 Conclusions

We investigate the weak (non-ergodic) convergence of an inertial proximal-gradient method with penalization terms in connection with the solving of a bilevel optimization problem, having as objective the sum of a convex nonsmooth with a convex smooth function, and as constrained set the set of minimizers of another convex and differentiable function. The techniques of the proof combine tools specific to inertial algorithms [3] and penalty type methods [5, 8]. We show the convergence of both generated iterates and objective function values.



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